

EE -171 SIGNALS AND SYSTEMS
FINAL EXAM
December 16, 2008
8:00 a.m. - 11:00 a.m.

Do all problems.
Each problem is 10 points.

NAME SOLUTIONS

1. _____
2. _____
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10. _____

Formulae:

$$\begin{aligned}x(t) &= \sum_{k=-\infty}^{+\infty} a_k e^{jk\Omega_0 t} \\a_k &= \frac{1}{T} \int_T x(t) e^{-jk\Omega_0 t} dt \\x(t) &= \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(\Omega) e^{j\omega_0 t} d\omega \\X(\Omega) &= \int_{-\infty}^{+\infty} x(t) e^{-j\Omega t} dt \\x(t) &= \frac{1}{2\pi j} \int_{\sigma-j\infty}^{\sigma+j\infty} X(s) e^{st} ds \\X(s) &= \int_{-\infty}^{+\infty} x(t) e^{-st} dt \\y(t) &= \int_{-\infty}^{+\infty} x(\tau) h(t-\tau) d\tau \\y[n] &= \sum_{m=-\infty}^{+\infty} x[m] h[n-m] \\x[n] &= \sum_{k=-\infty}^{+\infty} a_k e^{jk(\frac{2\pi}{N})n} \\a_k &= \frac{1}{N} \sum_{n=-\infty}^{+\infty} x[n] e^{-jk(\frac{2\pi}{N})n} \\X(e^{j\omega}) &= \sum_{n=-\infty}^{+\infty} x[n] e^{-j\omega n} \\x[n] &= \frac{1}{2\pi} \int_{2\pi} X(e^{j\omega}) e^{j\omega n} d\omega \\e^{-at} u(t) = x(t) &\Leftrightarrow X(\omega) = \frac{1}{(j\omega+a)} \\tx(t) &\Leftrightarrow \frac{1}{(j\omega+a)^2} \\x(at) &\Leftrightarrow \frac{1}{|a|} X\left(\frac{j\omega}{a}\right) \\1 &\Leftrightarrow 2\pi\delta(\omega) \\Cos\omega_0 t &\Leftrightarrow \pi\delta(\omega - \omega_0) + \pi\delta(\omega + \omega_0)\end{aligned}$$

(Note: There are a total of 100 points.)

1. (Signal power and signal energy)

Determine the (average) signal power of the following signals:

(a) $x(t) = A$

(b) $x(t) = \sin(t)$. {Recall: $\cos^2(t) = \frac{1}{2}(1 + \cos 2t)$ }

Determine the energy of the following signal:

(a) $x(t) = e^{-t}u(t)$.

$$(a) \boxed{\text{Pave}} = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T A^2 dt = \lim_{T \rightarrow \infty} \frac{1}{2T} A^2 t \Big|_{-T}^T = \lim_{T \rightarrow \infty} \frac{1}{2T} A^2 (2T) = \boxed{A^2}$$

$$(b) \sin(t+2\pi) = \sin t \quad \therefore T_0 = 2\pi$$

$$\therefore \text{Pave} = \frac{1}{2\pi} \int_{-\pi}^{+\pi} \sin^2 t dt = \frac{1}{2\pi} \int_{-\pi}^{+\pi} [1 - \frac{1}{2}(1 + \cos 2t)] dt$$

$$= \frac{1}{2\pi} \int_{-\pi}^{+\pi} (\frac{1}{2} - \frac{1}{2} \cos 2t) dt = \frac{1}{2\pi} \int_{-\pi}^{+\pi} \frac{1}{2} dt - \frac{1}{2\pi} \int_{-\pi}^{+\pi} \frac{1}{2} \cos 2t dt$$

$$\boxed{\text{Pave}} = \frac{1}{2\pi} (\frac{1}{2}) [t]_{-\pi}^{+\pi} - 0 = (\frac{1}{2\pi}) (\frac{1}{2}) (2\pi) = \boxed{\frac{1}{2}}$$

$$(c) \text{Energy} = \int_{-\infty}^{+\infty} x^2(t) dt = \int_{-\infty}^{+\infty} e^{-2t} u(t) dt = \int_0^{\infty} e^{-2t} dt$$

$$= \frac{1}{-2} [e^{-2t}]_0^{\infty} = \frac{1}{-2} [0 - 1] = \boxed{\frac{1}{2}}$$

2. (Differential equations)

Consider the first order linear time-invariant system given by,

$$\frac{dy}{dt} + 4y(t) = x(t) \quad (1)$$

where the system is initially at rest.

(a) When the input $x(t) = e^{-t}u(t)$ determine the total solution $y(t)$ for all $t \geq 0$.

(b) For the case where the input is $x(t) = \delta(t)$, show that the impulse response is

$$h(t) = e^{-4t}u(t).$$

(For initial conditions, in order to determine value of $y(t)$ immediately after application of the unit impulse, consider integrating (1) from $t = 0^-$ to $t = 0^+$. Hence determine $y(0^+)$. Assume $\int_{0^-}^{0^+} y(t)dt = 0$.)

(c) Using the impulse response of (b) and input $x(t)$ of (a), determine $y(t) = h(t) * x(t)$ and compare with $y(t)$ found in (a).

(a) $\frac{dy}{dt} + 4y = x(t)$

$y_H(t)$: $\frac{dy_H(t)}{dt} + 4y_H(t) = 0$ Try $y_H(t) = Ke^{st}$
 $\therefore sKe^{st} + 4Ke^{st} = 0$ $Ke^{st}(s+4) = 0$ $s = -4$
 $\therefore y_H(t) = Ke^{-4t}$

$y_P(t)$ $\frac{dy(t)}{dt} + 4y(t) = e^{-t}$ $t > 0$
 Try $y_P(t) = Ae^{-t}$
 $\therefore -Ae^{-t} + 4Ae^{-t} = e^{-t}$ $\therefore 3Ae^{-t} = e^{-t}$. Yes, if $A = \frac{1}{3}$
 $\therefore y_P(t) = \frac{1}{3}e^{-t}$

y_{TOTAL} = $y_H(t) + y_P(t) = Ke^{-4t} + \frac{1}{3}e^{-t}$
 $y(0) = 0 = K + \frac{1}{3} \Rightarrow K = -\frac{1}{3}$ $\therefore y_{TOTAL}(t) = \left(-\frac{1}{3}e^{-4t} + \frac{1}{3}e^{-t}\right)u(t)$



$$(b) \frac{dy}{dt} - 4y(t) = \delta(t)$$

$$\text{For } t > 0 \quad \frac{dy}{dt} + 4y(t) = 0 \Rightarrow y(t) = Ae^{-4t}$$

$$\text{I.C.} \quad \int_{0^-}^{0^+} \frac{dy}{dt} dt + \int_{0^-}^{0^+} 4y(t) dt = \int_{0^-}^{0^+} \delta(t) dt$$

$$\therefore y(0^+) - y(0^-) + 0 = 1 \quad \therefore y(0^+) = 1$$

$$\therefore \text{applying I.C. } y(0^+) = 1 = Ae^0 \Rightarrow A = 1$$

$$\therefore \boxed{h(t) = e^{-4t} u(t)}$$

$$(c) y(t) = h(t) * x(t) = e^{-4t} u(t) * e^{-t} u(t)$$

$$= \int_{-\infty}^{\infty} e^{-4\tau} u(\tau) e^{-(t-\tau)} u(t-\tau) d\tau = \int_0^t e^{-3\tau} d\tau e^{-t} \quad \underline{t \geq 0}$$

$$= e^{-t} \left[\frac{1}{-3} (e^{-3\tau}) \Big|_0^t \right] = \frac{e^{-t}}{-3} (e^{-3t} - 1)$$

$$\boxed{y(t) = \left(\frac{e^{-4t}}{-3} + \frac{1}{3} e^{-t} \right) u(t)}$$

3. (Difference equations)

(a) Consider the discrete LTI system represented by

$$y[n] = x[n] - x[n-1]$$

where the system is initially at rest. Determine impulse response $h[n]$. Plot it. Is the system stable?

(b) Now consider the discrete LTI system given by

$$y[n] = y[n-1] + x[n]$$

where the system is initially at rest. Determine the impulse response $h[n]$. Plot it. Is the system stable?

(c) For the system in (b), determine step response $y[n]$ when $x[n] = u[n]$. Plot it.

(a) $y[n] = x[n] - x[n-1]$ $x[n] = \delta[n]$

$\therefore h[n] = \delta[n] - \delta[n-1]$

$\sum_{n=-\infty}^{+\infty} |h[n]| = |h[0]| + |h[1]| = 1 + 1 = 2 < \infty$ \therefore STABLE

(b) $y[n] = y[n-1] + x[n]$ $x[n] = \delta[n]$

For $n > 0$ $y[n] - y[n-1] = 0$

Try $y[n] = A\alpha^n$ $\therefore A\alpha^n - A\alpha^{n-1} \stackrel{?}{=} 0$

i.e. $A\alpha^n [1 - \alpha^{-1}] \stackrel{?}{=} 0$ Yes, if $\alpha = 1$

$\therefore y[n] [h[n]] = A1^n \quad n > 0$

$y[0] = y[-1] + 1 \quad \therefore y[0] = 1$

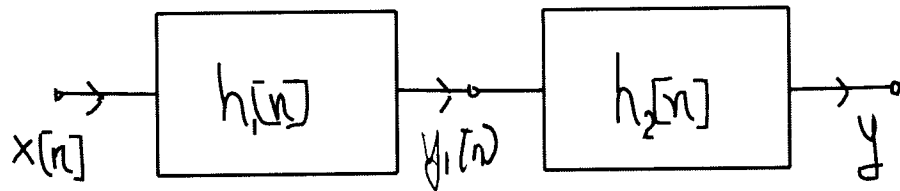
$\sum_{n=-\infty}^{+\infty} |h[n]| = \sum_{n=0}^{\infty} 1 = \infty$

Using the fact $h[n] = 1 \quad n \geq 0$

\therefore UNSTABLE

(c) $y[n] = u[n] + u[n] = \sum_{m=0}^n 1 = (n+1)u[n]$

4. (Discrete-time convolution)



Consider the cascade of two discrete-time LTI systems where,

$$\begin{aligned} x[n] &= (0.5)^n u[n] \\ h_1[n] &= u[n+3] \\ h_2[n] &= \delta[n] - \delta[n-1] \end{aligned}$$

Determine output $y[n]$.

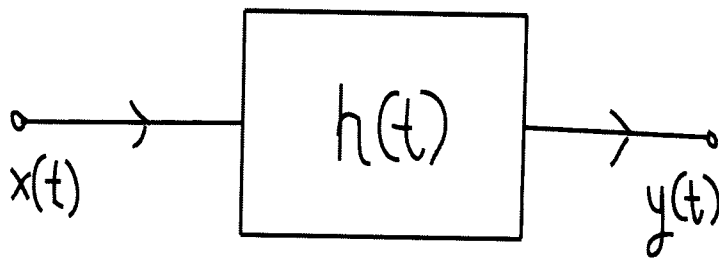
$$(i) \quad y_1[n] = \sum_{m=-\infty}^{+\infty} (0.5)^m u[m] u[n-m+3] = \sum_{m=0}^{n+3} (0.5)^m = \frac{1 - (0.5)^{n+4}}{1 - (0.5)} \quad n+3 \geq 0$$

$$\therefore y_1[n] = (2 - 2(0.5)^{n+4}) u[n-3]$$

$$(ii) \quad y[n] = y_1[n] * [\delta[n] - \delta[n-1]] \\ = y_1[n] - y_1[n-1]$$

$$y[n] = [2 - 2(0.5)^{n+4}] u[n-3] - [2 - 2(0.5)^{n+3}] u[n-4]$$

5. (Continuous-time convolution)



Let the input to a LTI system be $x(t) = e^{-2t}u(t)$. Consider the situation when the impulse response has a "natural frequency" which is the same as that of the excitation. That is, $h(t) = e^{-2t}u(t)$. Do the following:

- What is the natural frequency of the system?
- Determine $y(t)$ using continuous-time domain convolution.

$$(a) \quad h(t) = e^{-2t}u(t) \quad e^{st}u(t) \Big|_{s=-2} \quad \boxed{s=-2}$$

$$(b) \quad y(t) = \int_{-\infty}^{+\infty} x(\tau)h(t-\tau)d\tau = \int_{-\infty}^{+\infty} e^{-2\tau}u(\tau)e^{-2(t-\tau)}u(t-\tau)d\tau$$

$$= \int_0^t e^{-2\tau}e^{+2\tau}d\tau e^{-2t} \quad t \geq 0$$

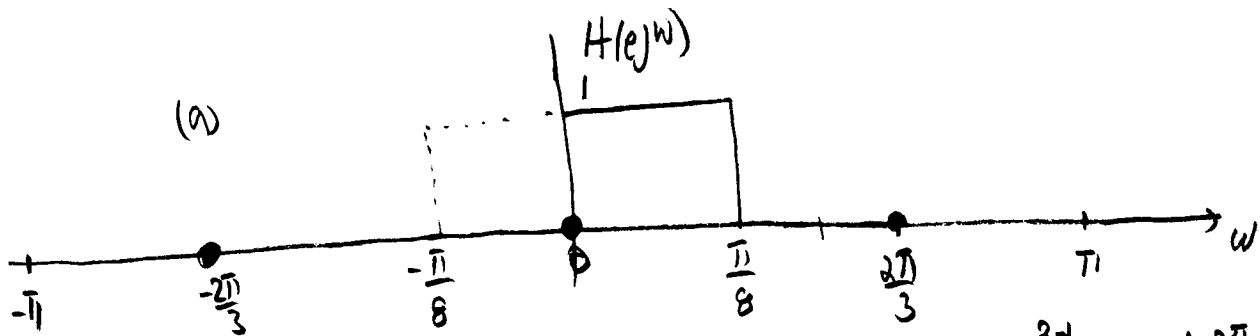
$$\boxed{y(t)} = \int_0^t 1d\tau e^{-2t} = \boxed{te^{-2t}u(t)}$$

6. (Discrete-time Fourier series, frequency response and output)

Consider a LTI digital filter with impulse response $h[n]$ and frequency response $H(e^{j\omega})$ where

$$H(e^{j\omega}) = \begin{cases} 1, & |\omega| \leq \frac{\pi}{8} \\ 0, & \frac{\pi}{8} < |\omega| < \pi \end{cases}$$

- (a) Sketch $H(e^{j\omega})$ for $0 \leq \omega \leq \pi$.
- (b) Consider an input signal $x[n]$ to the digital filter, where $x[n]$ is a periodic signal with period 3. It will have three Fourier coefficients. What are the three frequencies associated with these three coefficients? (Note: You do not need to find the Fourier coefficients. Just the frequencies at which they would occur in a 3-point discrete-time Fourier series).
- (c) Show that the output $y[n]$ will have only one Fourier series coefficient per period.



(b) $x[n] = x[n+3]$ $N=3$ $\therefore x[n] = \sum_{k=0}^{3-1} \tilde{a}_k e^{j\frac{2\pi}{3}kn}$

$$\therefore x[n] = \tilde{a}_0 e^0 + \tilde{a}_1 e^{j\frac{2\pi}{3}1n} + \tilde{a}_2 e^{j\frac{2\pi}{3}2n}$$

3 Fourier coeffs. at

frequencies $\left| 0, \frac{2\pi}{3}, \frac{4\pi}{3} \right|$

Equivalently $0, \frac{2\pi}{3}, -\frac{2\pi}{3}$

(c) only the dc component gets through.

7. (Continuous-time Fourier series)

Consider the causal continuous-time LTI system of problem (2) whose input $x(t)$ and output $y(t)$ are related by the following differential equation,

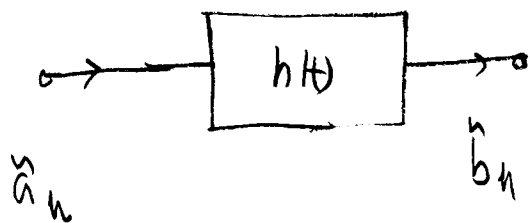
$$\frac{d}{dt}y(t) + 4y(t) = x(t).$$

Find the output $y(t)$ when the input $x(t) = \cos 2\pi t$, $-\infty < t < +\infty$. (Note that you can do this, assuming you have a periodic input. Then the output will also be periodic).

System $\frac{dy}{dt} + 4y(t) = x(t)$

$$h(t) = e^{-4t} u(t)$$

$$\therefore |A(j\Omega) = \frac{1}{j\Omega + 4}$$

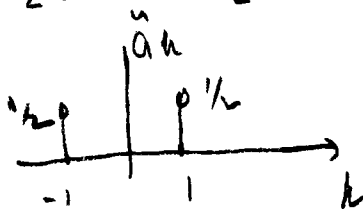


$$\tilde{b}_n = \tilde{a}_n H(j\Omega)$$

$\Omega = k\Omega_0$

$$x(t) = \frac{1}{2} e^{j2\pi t} + \frac{1}{2} e^{-j2\pi t}$$

$$\Omega_0 = 2\pi \quad T_0 = 1$$



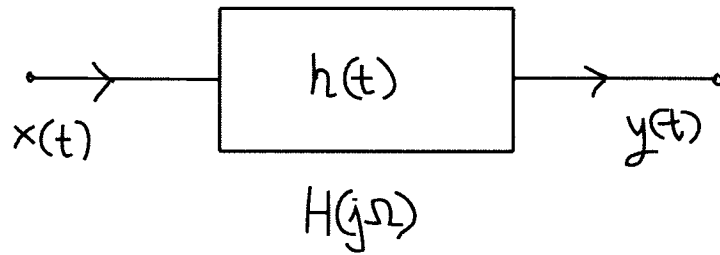
$$\tilde{b}_k = \tilde{a}_k \frac{1}{(jk\Omega_0 + 4)}$$

$$y(t) = \sum_{k=-1,1} \tilde{b}_k e^{jk2\pi t} = \frac{1}{2} \frac{e^{j(-1)2\pi t}}{j(-1)2\pi + 4} + \frac{1}{2} \frac{e^{j(1)2\pi t}}{j(1)2\pi + 4}$$

$$= \frac{1/2}{4 + j2\pi} e^{j2\pi t} + \frac{1/2}{4 - j2\pi} e^{-j2\pi t} = 2 \operatorname{Re} \left\{ \frac{1}{2} \frac{1}{\sqrt{16+4\pi^2}} e^{j2\pi t} e^{j\theta} \right\}$$

$$y(t) = \frac{1}{\sqrt{16+4\pi^2}} \cos(2\pi t - \theta) \quad \theta = \tan^{-1} \frac{\pi}{2}$$

8. (Fourier transform)



Consider a causal LTI systems with frequency response

$$H(j\omega) = \frac{1}{j\omega + 3}$$

For a particular signal $x(t)$, the output is observed to be

$$y(t) = e^{-3t}u(t) - e^{-4t}u(t)$$

(a) Determine $x(t)$.

(b) Give the differential equation describing the output $y(t)$ and input $x(t)$.

$$(a) \quad Y(j\Omega) = \frac{1}{j\Omega + 3} - \frac{1}{j\Omega + 4} = \frac{1}{(j\Omega + 3)(j\Omega + 4)} = H(j\Omega)X(j\Omega)$$

$$X(j\Omega) = \frac{1}{(j\Omega + 3)(j\Omega + 4) \cdot H(j\Omega)} = \frac{1}{j\Omega + 4}$$

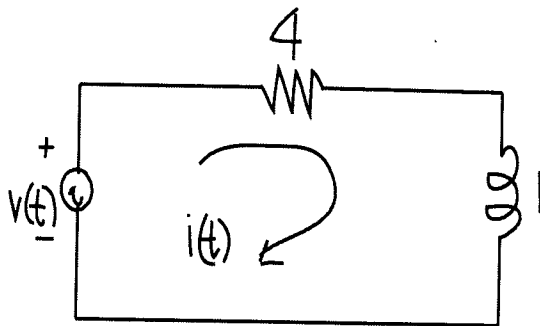
$$\boxed{\therefore x(t) = e^{-4t}u(t)}$$

$$(b) \quad \frac{Y(j\Omega)}{X(j\Omega)} \stackrel{a}{=} H(j\Omega) = \frac{1}{j\Omega + 3}$$

$$\therefore (j\Omega + 3)Y(j\Omega) = X(j\Omega)$$

$$\boxed{\therefore \frac{dy}{dt} + 3y(t) = x(t)}$$

9. (Laplace transform)



Assume that a voltage $v(t) = e^{-3t}u(t)$ is applied at $t = 0$. Using Laplace transforms, find output current $i(t)$ for $t \geq 0$. Assume all initial conditions are zero.

$$1 \frac{di(t)}{dt} + 4i(t) = v(t) = e^{-3t}u(t)$$

$$sI(s) - \cancel{i(0^-)} + 4I(s) = \frac{1}{s+3}$$

$$I(s)[s+4] = \frac{1}{s+3} \quad I(s) = \frac{1}{(s+3)(s+4)} = \frac{A}{s+3} + \frac{B}{s+4}$$

$$= \frac{1}{s+3} - \frac{1}{s+4}$$

$$\therefore i(t) = e^{-3t}u(t) - e^{-4t}u(t)$$

10. (Laplace Transform)

For the following transfer functions $H(s)$, show the poles on the s -plane for each transfer function. Determine the corresponding time-domain response.

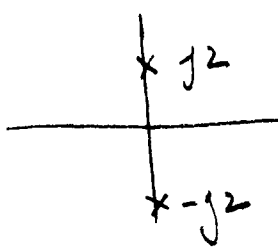
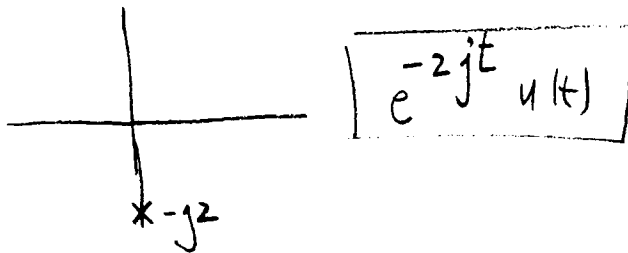
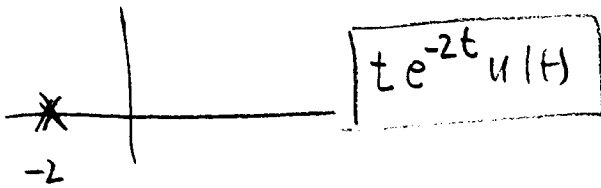
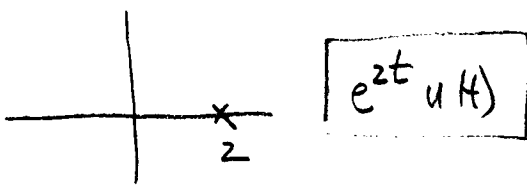
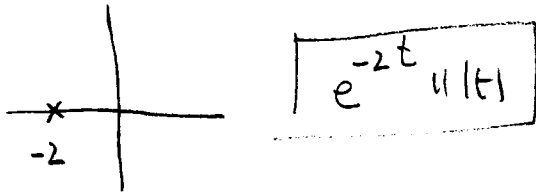
$$H(s) = \frac{1}{s+2}, \quad \text{Re}\{s\} > -2$$

$$H(s) = \frac{1}{s-2}, \quad \text{Re}\{s\} > 2$$

$$H(s) = \frac{1}{(s+2)^2}, \quad \text{Re}\{s\} > -2$$

$$H(s) = \frac{1}{s+j2}, \quad \text{Re}\{s\} > 0$$

$$H(s) = \frac{1}{s^2+4}, \quad \text{Re}\{s\} > 0$$



$$e^{j2t} u(t) + e^{-j2t} u(t) = \boxed{2 \cos t u(t)}$$